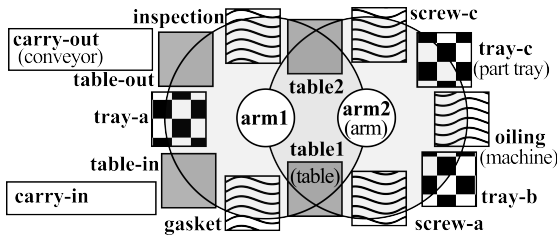


Mass-Manufacturing Domain and Loop Unrolling Strategy

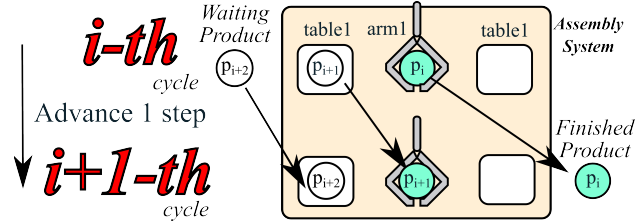


CELL-ASSEMBLY \approx Gripper + Woodworking + Logistics
(based on [Ochi et al, SPARK2013])

- Assemble and paint products while moving them with arms between tables or special purpose machines
- also a *temporal* problem (actions execute in parallel)

Large-scale problems in factory assembly require the manufacturing of **100's or 1000's of identical products**.

We used the cyclic structure of the domain.



Everything except indices of the products are the same after a cycle. Each loop path is identified by Steady State (SS) \equiv a state in the beginning of one cycle, indexed with i .

ex. S_i : (at p_{i+1} table), (at p_i arm), (painted p_i).

Build a large plan by unrolling the same loop.

Two challenges for fully automated cyclic plan synthesis

WHICH STATES are Steady States? : Problem 1

- Search all states from Init and test them \rightarrow impractical.
- Labelling some objects (table, machine) and predicates (at) ? \rightarrow Possible, but domain-dependent

Which Steady State yields the best cyclic plan? : Problem 2

- Brute force search \rightarrow impractical
- \therefore testing each SS invokes a *standard STRIPS planner each time*

ACP : Finding Efficient Loops based on Domain Independent Analysis

1. Main contribution: Owner / Lock

A unit capacity resource \approx a place.

use table1 \in Attach @ table1.

A predicate being "a place or not"?

not trivial : syntactically they look the same
Is this a place? (human understanding)

(color ?p red) no,maybe
(at ?p table1) yes,maybe
(pred ?p X) **hmm, no idea**

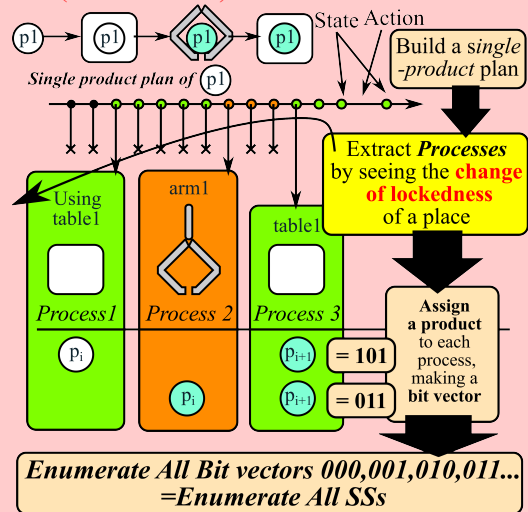
\Leftrightarrow **Observation**: table1 may be "(used table1)".

Now we have a fully automated method:
Predicate $o = (P X_1 X_2 \dots)$ is a place when there is a lock predicate l that satisfies:

- If a occupies o , check if the place o is not in use, and acquire the lock l .
- If a leaves o , release the lock l .

No assumptions about domain. \rightarrow **Applicable to any STRIPS input**

2. Extract processes from a plan to enumerate SSs (Solves Prob.1).



3. Pruning SSs (Solves Prob.2) if they are:

	table1	arm1	table1
Infeasible	1	0	1
Deadlock	1	1	0
Duplicated*	1	0	0
	0	1	0

(* They are the same loop)
Highly effective - e.g., on CELL-ASSEMBLY problem instance, reduced # of candidates from 5×10^6 to 677.

Plan each cycle from S_i to S_{i+1} , get the least-makespan cyclic plan, and generate N instance plan by unrolling i , **with no additional computational cost!**

Experiments

- ACP vs 5 planners (FD/LMcut+postprocessing scheduler, FD/LAMA+postprocessing scheduler, yahsp, DAE, CPT) vs (best score of) 5 Simple Cyclic Planner (SCP).
- SCP: solve $K = \{1, \dots, 9\}$ products plan with above 5 planners and get the mean makespan per product. Some even failed to solve $K = 9$
- 5 CELL-ASSEMBLY, modified IPC Temporal Woodworking, unmodified IPC Barman.
- ACP solved **all instances**.
- Standard planners failed for $N \geq 16$.
- ACP was significantly better than SCP.
- Gap relative to lbound is reasonably good.
- Automatically detected owner/lock structure in standard IPC problems** and generated cyclic solutions.

Problem	# of products	run-time [sec]	ACP makespan (per product)		SCP makespan (per product)		manual lbound	CPT(h2) lbound	gap (ACP / max. lbound)
			e_{ACP}	e_{ACP}/N	e_{SCP}/K	l_m			
CELL-ASSEMBLY 1	4	1048	331	82.8	83 ($K=2$)	156	176.3	1.9	
	16	1049	1255	78.4	FD/LMcut	624	460	2.0	
	1024	1050	78871	77.0	(+ scheduler)	39936	fail	2.0	
CELL-ASSEMBLY 2	4	34	246	61.5	62.3 ($K=3$)	168	181.12	1.4	
	16	33	978	61.1	FD/LMcut	672	593	1.5	
	1024	35	62466	61.0		43008	fail	1.5	
CELL-ASSEMBLY 3	4	1893	660	165	171 ($K=1$)	176	237	2.8	
	16	1953	2352	147	FD/LAMA	704	345	3.3	
	1024	1973	144480	141.1		45056	fail	3.2	
CELL-ASSEMBLY 4	4	1163	318	79.5	81.3 ($K=3$)	112	191	1.7	
	16	1162	1074	67.1	FD/LMcut	448	240	2.4	
	1024	1165	64578	63.1		28672	fail	2.3	
CELL-ASSEMBLY 5	4	1968	804	201	203 ($K=1$)	172	335	2.4	
	16	1856	2508	156.8	FD/LMcut	688	532	3.6	
	1024	1894	145644	142.2		44032	fail	3.3	
WW product : parts	4	11	80	20	17.2 ($K=9$)	60	80	1	
	16	11	260	16.3	FD/LAMA	240	185	1.1	
	1024	15	15380	15.0		15360	fail	1.0	
Barman product : cocktail	4	331	35	8.8	6.3 ($K=4$)	4	21	1.7	
	16	332	179	11.2	FD/LMcut	16	26	6.9	
	1024	332	12275	12.0		1024	fail	12.0	

Conclusions

Owner/lock method is applicable to **general STRIPS input**

Owner/lock exists in IPC domains

Solved large problems by simply unrolling the loop many times (negligible marginal cost)